

# On Mean-Square and Asymptotic Stability for Numerical Approximations of Stochastic Ordinary Differential Equations

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## Abstract

This note tries to connect the stochastic mean-square stability [Saito and Mitsui, SIAM J. Numer. Anal., 33(1996), pp. 2254-2267] and the asymptotic stability [D.J. Higham, SIAM J. Numer. Anal., 38(2000), pp. 753-769]. SAITO and MITSUI generalizes the deterministic A-stability for a stochastic differential equation test problem with multiplicative noise. For the test equation, we know that the asymptotic stability in the mean-square sense implies the stochastic asymptotic stability in large. We will prove the same property for numerical schemes.

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## 1 Introduction

We consider the scalar stochastic initial value problem (SIVP) for the Itô ordinary differential equations (SODE) given by :

$$dX(t) = a(t, X(t))dt + b(t, X(t))dW(t) \quad \text{for } 0 \leq t \leq T \quad \text{and} \quad X(t) \in \mathbb{R}, \quad (1)$$

where functions are defined by

$$a : [0, +\infty) \times \mathbb{R} \rightarrow \mathbb{R}, \quad b : [0, +\infty) \times \mathbb{R} \rightarrow \mathbb{R} \quad \text{and} \quad X(0) = X_0,$$

and  $W(t)$  is the 1-dimensional Brownian motion. Let  $\mathcal{F}_t$  denote the increasing family of  $\sigma$ -algebras (filtration) generated by the Brownian motion  $W(s), s \leq t$ . Details about this stochastic object and corresponding calculus can be found in [1, 4].

We consider an Itô equation (1) with a steady solution  $X_t \equiv 0$ . This means that  $a(t, 0) = b(t, 0) = 0$  holds.  $X^{t_0, 0}(t)$  means that  $X^{t_0, 0}(t_0) = 0$ .

The following definitions are due to HASMINSKI:

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**Definition 1** *The steady state solution  $X^{t_0,0}(t) \equiv 0$  of (1) is said to be **stochastically stable** if for any  $\epsilon > 0$  and  $t_0 \geq 0$*

$$\lim_{x_0 \rightarrow 0} P(\sup_{t \geq t_0} \|X^{t_0, x_0}(t)\| \geq \epsilon) = 0.$$

**Definition 2** *The steady state solution  $X^{t_0,0}(t) \equiv 0$  of (1) is said to be **stochastically asymptotically stable** if, in addition to being stochastically stable,*

$$\lim_{x_0 \rightarrow 0} P(\lim_{t \rightarrow +\infty} \|X^{t_0, x_0}(t)\| = 0) = 1.$$

**Definition 3** *The steady state solution  $X^{t_0,0}(t) \equiv 0$  of (1) is said to be **stochastically asymptotically stable in the large**, if moreover to the above two,*

$$P(\lim_{t \rightarrow +\infty} \|X^{t_0, x_0}(t)\| = 0) = 1. \text{ for all } x_0.$$

For the general SODE (1) KLOEDEN and PLATEN (cf. [5]) gave the following definition:

**Definition 4** *The steady state solution  $X^{t_0,0}(t) \equiv 0$  of (1) is **stable in the  $p$ -th mean** if for*

$$\forall \epsilon > 0 \forall t_0 > 0, \exists \delta = \delta(t_0, \epsilon) > 0$$

*such that*

$$E \|X^{t_0, x_0}(t)\|^p < \epsilon$$

*for all  $t \geq t_0$  and  $\|x_0\| < \delta$ .*

**Definition 5** *The steady state solution  $X^{t_0,0}(t) \equiv 0$  of (1) is **asymptotically stable in the  $p$ -th mean** if in addition, there exists a  $\delta_0 = \delta_0(t_0)$  such that*

$$\lim_{t \rightarrow +\infty} E \|X^{t_0, x_0}(t)\|^p = 0 \text{ for all } \|x_0\| < \delta_0.$$

The most frequently used case  $p = 2$  is called the mean-square case and in the sequel we focus our investigation on the mean-square stability.

We suppose that the equation (1) has a unique, bounded strong solution  $X(t)$  in the mean-square sense.

Usual deterministic time discretization of a bounded time-interval  $[0, T]$ ,  $T > 0$  is of the form  $0 = t_0 < t_1 < \dots < t_N = T$ , where  $N$  is a natural number. We suppose that  $t_0 = 0$  and adopt an equidistant discretization with the step size  $\Delta = t_{n+1} - t_n$ ,  $n = 0, 1, \dots, N - 1$ .

In the sequel  $Y_n$  always denotes the approximation of  $X(t_n)$  using a given numerical scheme with the step size  $\Delta$ .

## 2 Mean-square and asymptotic stabilities for the test equation

Consider the one-dimensional stochastic test equation

$$dX(t) = \lambda X(t)dt + \mu X(t)dW(t) \quad (t \geq 0), \quad X(0) = x_0, \quad (2)$$

where  $\lambda$  and  $\mu$  are complex numbers and we assume that  $x_0$  is a non zero deterministic value.

The exact solution of (2) is

$$X(t) = \exp\left(\left(\lambda - \frac{\mu^2}{2}\right)t + \mu W(t)\right) x_0,$$

which is sometimes called geometric Brownian motion. It has the second moment

$$E|X(t)|^2 = \exp((2\Re(\lambda) + |\mu|^2)t)|x_0|^2.$$

For this test equation, the stationary solution  $X(t) \equiv 0$  is stochastically asymptotically stable in large if the inequality

$$\Re\left(\lambda - \frac{1}{2}\mu^2\right) < 0$$

holds. SAITO-MITSUI [6] showed that the zero solution of equation (2) is asymptotically mean-square stable if and only if

$$2\Re(\lambda) + |\mu|^2 < 0,$$

as we can see the form of the second moment of  $X(t)$ .

Note that since the inequality  $\Re(2\lambda - \mu^2) \leq 2\Re(\lambda) + |\mu|^2$  is always valid, the asymptotic stability in the mean-square sense implies the stochastic asymptotic stability in large.

As considered in [2] and [6] the analytical theory is not applicable to numerical schemes because it is impossible to carry out a numerical scheme until all the sample paths (2) diminish to zero if  $\Re(\lambda) > 0$  and  $\Re(\lambda - \frac{1}{2}\mu^2) < 0$ .

Generally, in the vector case, when we apply a numerical scheme ( $Y_n$ ) to the equation (2) and take the mean-square norm, we obtain a one-step difference equation of the form

$$E \| Y_{n+1} \|^2 = R(\bar{\Delta}, k) E \| Y_n \|^2, \quad (3)$$

where  $\bar{\Delta} = \Delta\lambda$  and  $k = -\mu^2/\lambda$ .

SAITO and MITSUI in their work [6] called the function  $R(\bar{\Delta}, k)$  as the stability function of the scheme. In this case  $E \| Y_n \|^2 \rightarrow 0$  as  $n \rightarrow +\infty$  iff

$$|R(\bar{\Delta}, k)| < 1.$$

They gave in their work [6] the following definition:

**Definition 6** *The scheme is said to be MS-stable for those values of  $\overline{\Delta}$  and  $k$  satisfying*

$$|R(\overline{\Delta}, k)| < 1. \quad (4)$$

The set  $\mathcal{R}$  given by

$$\mathcal{R} = \{(\overline{\Delta}, k) : |R(\overline{\Delta}, k)| < 1\}$$

is analogously called the domain of MS-stability of the scheme.

HIGHAM [3] introduces the new concept of stability.

**Definition 7** *When a numerical scheme is applied to the stochastically asymptotically stable in large as equation (2) and generating the sequence  $(Y_n)$ , it is said to be numerically asymptotically stable in large (or simply, asymptotically stable) if*

$$\lim_{n \rightarrow +\infty} \|Y_n\| = 0 \quad (5)$$

with probability 1.

We can establish a relationship between two stability concepts as follows.

**Theorem 1** *The MS-stable schemes satisfying (4) are numerically asymptotically stable in large.*

In the proof of Theorem we will use the statement of the following Lemma.

**Lemma 1**

$$\lim_{n \rightarrow +\infty} \|Y_n\| = 0 \text{ (a.s.)}$$

iff

$$\lim_{n \rightarrow +\infty} P(\cup_{k=n}^{\infty} \{\|Y_k\| \geq \epsilon\}) = 0 \quad \text{for all } \epsilon > 0. \quad (6)$$

*Proof of Lemma.* We prove this statement by defining for  $n \in \mathbb{N}$  and  $\epsilon > 0$  the events

$$A_n(\epsilon) = \{\|Y_n\| \geq \epsilon\}$$

and

$$A(\epsilon) = \overline{\lim}_n A_n(\epsilon) = \cap_{n=1}^{+\infty} \cup_{k=n}^{+\infty} A_k(\epsilon).$$

We notice that since  $\cup_{k=n}^{+\infty} A_k(\epsilon) \downarrow A(\epsilon)$  as  $n \rightarrow +\infty$ , the equality  $P(A(\epsilon)) = \lim_{n \rightarrow +\infty} P(\cup_{k=n}^{+\infty} A_k(\epsilon))$  holds.

Now we define an event

$$D = \{\omega \in \Omega; \|Y_n\| \text{ does not converge to } 0 \text{ as } n \rightarrow +\infty\}.$$

Then

$$D = \cup_{\epsilon > 0} A(\epsilon) = \cup_{m=1}^{+\infty} A\left(\frac{1}{m}\right),$$

because of  $A(\epsilon_1) \subset A(\epsilon_2)$  for  $\epsilon_1 > \epsilon_2$ .

The above equalities imply that  $\lim_{n \rightarrow +\infty} \|Y_n\| = 0$  with probability 1 that is equivalent to  $P(D) = 0$ . It holds only if and only if  $P(A(\epsilon)) = 0$  for all  $\epsilon > 0$ , which is equivalent to

$$\lim_{n \rightarrow +\infty} P(\cup_{k=n}^{\infty} \{\|Y_k\| \geq \epsilon\}) = 0 \quad \text{for all } \epsilon > 0. \quad (7)$$

■

Using this result we can prove the statement of the Theorem.

*Proof of Theorem.*

We estimate the right-hand side of the inequality (7)

$$\begin{aligned} P(\cup_{l=n}^{\infty} \{\|Y_l\| \geq \epsilon\}) &\leq \sum_{l=n}^{\infty} P(\|Y_l\| \geq \epsilon) \leq \sum_{l=n}^{\infty} \frac{E \|Y_l\|^2}{\epsilon^2} \\ &\leq \sum_{l=n}^{\infty} \frac{R(\bar{\Delta}, k)^l E \|Y_0\|^2}{\epsilon^2} \leq \frac{E \|Y_0\|^2}{\epsilon^2} \sum_{l=n}^{\infty} R(\bar{\Delta}, k)^l \end{aligned}$$

tends to 0 as  $n \rightarrow +\infty$  due to the condition (4) for all  $\epsilon > 0$ . Now we attain

$$\lim_{n \rightarrow \infty} \|Y_n\| = 0 \quad (\text{a.s.})$$

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By this we have the same conclusion as for exact solution: all MS-stable schemes are asymptotically stable in large.

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